Automation (21-541)

Advanced Manufacturing Laboratory

Department of Industrial Engineering

Sharif University of Technology

Session # 14



Session Schedule

- Computer-Aided Process Planning (CAPP)
 - *CAPP integration with CAD*
 - Computer-Aided Process Planning based on CAD software solutions
 - Mapping the Extracted Manufacturing Features to Process Planning
 - Intelligent Feature Recognition Methodology (IFRM) Implementation

- Process planning primitives
 - Process planning is concerned with determining the sequence of individual manufacturing operations needed to produce a given part or product.
 - The resulting operation sequence is documented on a form typically referred to as operation sheet.
 - The operation sheet is a listing of the production operations and associated machine tools for a work part or assembly.
 - Process planning is an important stage of product development since production tool
 jigs, fixtures, special tools etc. can be designed only after the process plan is finalized

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Computer-Aided Process planning (CAPP)

- Process planning primitives
 - The current approaches for computer aided process planning can be classified into two groups:
 - Variant
 - Generative



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- Implementation consideration
 - Mapping the Extracted Manufacturing Features to Process Planning
 - After extracting the manufacturing features from the designed part, it is necessary to map all the extracted manufacturing features to the process planning point of view as an application of CAM.
 - It is necessary to determine the detailed machining information for each feature and the designed part by identifying:
 - The operation sequence of the designed part,
 - The operation type,
 - The machine,
 - The cutting tool,
 - The tool approach/machining direction, and
 - The removed machining volume for each feature.

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Computer-Aided Process planning (CAPP)

- Implementation consideration
 - Mapping the Extracted Manufacturing Features to Process Planning
 - Machining operations

The main objective of any machining operation is to create the required shape of the designed part by removing the excess material from the work piece in form of chips.

- Turning,
- Milling,
- Drilling,
- Grinding,
- Broaching and
- Sawing.

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- *Implementation consideration*
 - Mapping the Extracted Manufacturing Features to Process Planning

| No. | Feature | Operation Type | Machine | Cutting Tool |
|-----|-----------------|-------------------|----------|--------------------------------|
| 1 | Step Through | Shoulder_Milling | Milling | Side Milling Cutter |
| 2 | Slot Through | Slotting_Milling | Milling | End mill Cutter |
| 3 | Step Blind | Shoulder_Milling | Milling | Side Milling Cutter |
| 4 | Slot Blind | Slotting_Milling | Milling | End Milling Cutter |
| 5 | Pocket Through | Pocket_Milling | Milling | End Milling Cutter |
| 6 | Pocket Blind | Pocket_Milling | Milling | End Milling Cutter |
| 7 | Hole Through | Drilling | Drilling | Twist Drill |
| 8 | Hole Blind | Drilling | Drilling | Twist Drill |
| 9 | Step Through RC | Shoulder_Milling | Milling | Corner Rounding Milling Cutter |

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Computer-Aided Process planning (CAPP)

- Implementation consideration
 - Mapping the Extracted Manufacturing Features to Process Planning
 - Machining Sequence Procedure
 - Machining Direction Procedure
 - Machining Information Procedure

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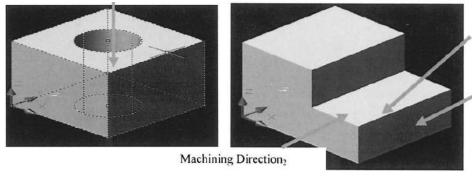
- Implementation consideration
 - Mapping the Extracted Manufacturing Features to Process Planning
 - Machining Sequence Procedure
 - For each feature recognized, its origin is designated as the point on the feature closest to the origin.
 - Sort all the features based upon the z coordinate (in descending order) of their respective origin.
 - The feature with the highest z value will be the first in machining sequence and the feature with the lowest z value will be the last in machining sequence.
 - Multiple features with same z value of their origin will be machined in the sequence in which they were originally recognized.

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Computer-Aided Process planning (CAPP)

- *Implementation consideration*
 - Mapping the Extracted Manufacturing Features to Process Planning
 - Machining Direction Procedure
 - Each feature has a different machining direction based on its design and orientation.
 - When a feature is recognized, its machining direction is also identified based on the directions that are available for machining that feature and also the orientation of the feature.
 - The directions are identified using crucial edges as references in every feature.

- *Implementation consideration*
 - Mapping the Extracted Manufacturing Features to Process Planning
 - Machining Sequence Procedure
 - Steps of machining direction procedure are addressed:



Basic Edge

Machining Direction

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Computer-Aided Process planning (CAPP)

- *Implementation consideration*
 - Mapping the Extracted Manufacturing Features to Process Planning
 - Machining Information Procedure
 - This procedure addresses how the machining operations, machines, and tools associated for each recognized feature are identified
 - A map of features to machining information is defined.
 - The program uses this map to associate each feature to the machining operations involved in creating that feature.
 - The mapped machining operations will indicate the machine to be used in machining the feature.
 - The program also map machining operations to tools that will be used with each such machining operation.
 - The machining volume (V) for each extracted manufacturing feature is calculated.

- Implementation consideration
 - Mapping the Extracted Manufacturing Features to Process Planning

| No. | Feature | Operation Type | Machine | Cutting Tool |
|-----|-----------------|-------------------|----------|--------------------------------|
| 1 | Step Through | Shoulder_Milling | Milling | Side Milling Cutter |
| 2 | Slot Through | Slotting_Milling | Milling | End mill Cutter |
| 3 | Step Blind | Shoulder_Milling | Milling | Side Milling Cutter |
| 4 | Slot Blind | Slotting_Milling | Milling | End Milling Cutter |
| 5 | Pocket Through | Pocket_Milling | Milling | End Milling Cutter |
| 6 | Pocket Blind | Pocket_Milling | Milling | End Milling Cutter |
| 7 | Hole Through | Drilling | Drilling | Twist Drill |
| 8 | Hole Blind | Drilling | Drilling | Twist Drill |
| 9 | Step Through RC | Shoulder_Milling | Milling | Corner Rounding Milling Cutter |

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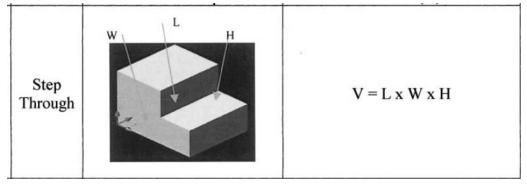
Computer-Aided Process planning (CAPP)

- Implementation consideration
 - Mapping the Extracted Manufacturing Features to Process Planning
 - Machining Information Procedure
 - The machining volume (V) for each extracted manufacturing feature is calculated.

Step through (with round corner)
 Slot through (with round corner)
 Pocket through (with round corner)
 Pocket Blind (with round corner)

Hole through Hole Blind
 Dovetail Slot V slot
 Cone Sink

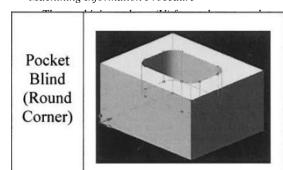
- Implementation consideration
 - Mapping the Extracted Manufacturing Features to Process Planning
 - Machining Information Procedure



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Computer-Aided Process planning (CAPP)

- Implementation consideration
 - Mapping the Extracted Manufacturing Features to Process Planning
 - Machining Information Procedure



 $V=LxWxH-4HxR^2+(\pi)R^2xH$

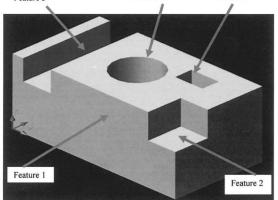
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- Implementation consideration
 - Intelligent Feature Recognition Methodology (IFRM) Implementation
 - At first we should generate the geometrical attributes of the designed part by CAD system and save them into a geometrical attributes file.
 - Then the feature recognition program will be executed to read and interpret this geometrical attributes and transform them into design information.

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Computer-Aided Process planning (CAPP)

- Implementation consideration
 - Intelligent Feature Recognition Methodology (IFRM) Implementation Feature 3 Feature 4



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- Implementation consideration
 - Intelligent Feature Recognition Methodology (IFRM) Implementation
 - Feature's extraction and classifications methodology:
 - Extract the geometry and topology entities for the designed object model from IGES file:
 - (a) Identify vertices, edges, faces, loops of the object.
 - Extract topology entities in each basic surface and identify its type:
 - (a) Identify the total number of loops in each surface.
 - (b) Identify the basic surface due to total number of loops.
 - (c) Classify the loops into different types (concave, convex, and hybrid).
 - Test the feature's existence in the basic surface based on loops

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Computer-Aided Process planning (CAPP)

- Implementation consideration
 - Intelligent Feature Recognition Methodology (IFRM) Implementation
 Table 10-1. Extraction of vertices

| NO. | Vertex | Coordinates | NO. | Vertex | Coordinates |
|------|--------|-------------|------|--------|-------------|
| 110. | ID | (X,Y,Z) | 110. | ID | (X,Y,Z) |
| 1 | [1] | (19,8,16) | 18 | [18] | (25,0,16) |
| 2 | [2] | (19,8,0) | 19 | [19] | (30,6,16) |
| 3 | [3] | (11,8,16) | 20 | [20] | (30,0,0) |
| 4 | [4] | (11,8,0) | 21 | [21] | (30,16,0) |
| 5 | [5] | (25,13,8) | 22 | [22] | (30,16,16) |
| 6 | [6] | (25,10,8) | 23 | [23] | (7,16,11) |
| 7 | [7] | (20,13,8) | 24 | [24] | (7,0,11) |
| 8 | [8] | (20,10,8) | 25 | [25] | (2,16,11) |
| 9 | [9] | (20,10,16) | 26 | [26] | (2,0,11) |

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- Implementation consideration
 - Intelligent Feature Recognition Methodology (IFRM) Implementation

Table 10-2. Extraction of edges (example 1)

| Edge | Edge | | Coordinates | | Length | Concavity |
|------|----------|----------------|-----------------|-----------|---------|-----------|
| ID | type | Starting point | Terminate point | Center | /Radius | Concavity |
| [1] | Line | [1] | [2] | | 16 | Tangent |
| [2] | Cir. Arc | [3] | [1] | (15,8,16) | 4 | |
| [3] | Line | [4] | [3] | | 16 | Tangent |
| [4] | Cir. Arc | [2] | [4] | (15,8,0) | 4 | |
| [5] | Line | [5] | [6] | | 3 | Concave |
| [6] | Line | [7] | [5] | | 5 | Concave |
| [7] | Line | [8] | [7] | | 3 | Concave |
| [8] | Line | [6] | [8] | | 5 | Concave |

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Computer-Aided Process planning (CAPP)

- *Implementation consideration*
 - Intelligent Feature Recognition Methodology (IFRM) Implementation

Table 10-3. Extraction of loops (example 1)

| 10010 | Tuble 10 3. Extraction of loops (example 1) | | | | | | |
|------------|---|---------------|------------|-----------------|--|--|--|
| Loop ID | Loop type | Loop category | Face ID | Edge ID | | | |
| [1] | External | Hybrid | [1] | [1][2][3][4] | | | |
| [2] | External | Concave | [2] | [5][6][7][8] | | | |
| [3] | External | Hybrid | [3] | [9][10][11][8] | | | |
| [4] | External | Hybrid | [4] | [12][13][9][7] | | | |
| [5] | External | Hybrid | [5] | [14][15][12][6] | | | |
| [6] | External | Hybrid | [6] | [11][16][14][5] | | | |
| | | | | | | | |

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- Implementation consideration
 - Intelligent Feature Recognition Methodology (IFRM) Implementation

Table 10-4. Extraction of faces (example 1)

| Face ID | Surface Type | Normal Vector | Concavity | Number of Loops | Loop ID |
|------------|-------------------------------|------------------|-----------|-----------------------|------------|
| [1] | Surface of revolution | | Concave | 1 | [1] |
| [2] | Plane Surface (parameterized) | (0,0,1) | Concave | 1 | [2] |
| [3] | Plane Surface (parameterized) | (0,1,0) | Concave | 1 | [3] |
| [4] | Plane Surface (parameterized) | (0,0-1) | Concave | 1 | [4] |
| [5] | Plane Surface (parameterized) | (0,-1,0) | Concave | 1 | [5] |
| [6] | Plane Surface (parameterized) | (-1,0,0) | Concave | 1 | [6] |
| [7] | Surface of revolution | | Concave | 1 | [7] |

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Computer-Aided Process planning (CAPP)

- *Implementation consideration*
 - Intelligent Feature Recognition Methodology (IFRM) Implementation
 - Feature's extraction and classifications methodology:
 - Identify feature type:
 - (a) Identify exterior form features (FFexterior) by searching for the hybrid loop.
 - (b) Identify interior convex form features (FFinterior) by searching for the convex loop.
 - (c) Identify interior concave form features (FFinterior) by searching for the concave loop.
 - Identify the detailed features and extract the related feature geometry parameters:
 - (a) Identify feature's details (number of surfaces, surface type).
 - (b) Identify the parameters of each feature: length (L), width (W), height (H), radius (R).
 - (c) Identify the relative location of each feature due to the origin coordinates of the object.

■ Implementation consideration

Intelligent Feature Recognition Methodology (IFRM) Implementation

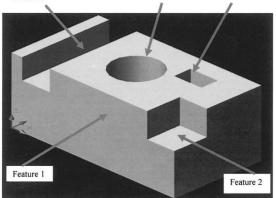
| Table 10-5. | Extraction | of features | (evample 1) |
|-------------|------------|-------------|-------------|
| Table 10-5. | Extraction | or reatures | (examble 1) |

| Feat. | Feature | Faces | Edges | Location | Feature | D | Dimensio | | n |
|-------|------------------------|------------------------------|---------------------------------|------------------|--------------|----|----------|----|---|
| ID | type | ID | ID | Location | name | L | W | Н | R |
| [1] | prismatic | [11][18][20] [15][18][19] | [29][30][37][40][44] | [32] = (0,0,0) | Raw Material | 30 | 16 | 16 | |
| | | | [45][47][49][50][51] | | | | | | |
| [2] | FF _{exterior} | [8][10][9] | [20][21][23] | [16] = (25,0,10) | Step_Blind | 6 | 6 | 5 | |
| [3] | FF _{exterior} | [13][12][14] | [34][[32] | [26] = (2,0,11) | Slot_Through | 16 | 5 | 5 | |
| [4] | FF _{interior} | [3][4][5][6][2] | [5][6][7][8] [9][12][14][11] | [8] = (20,10,8) | Pocket_Blind | 8 | 5 | 3 | |
| [5] | FF _{interior} | [1][7] | [1][2][3][4] [17][18] | (15,8,0) | Hole_Through | 16 | | | 4 |

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Computer-Aided Process planning (CAPP)

- Implementation consideration
 - Intelligent Feature Recognition Methodology (IFRM) Implementation
 Feature 3 Feature 5



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- Implementation consideration
 - Intelligent Feature Recognition Methodology (IFRM) Implementation
 - Feature's extraction and classifications methodology:
 - *Identify the detailed machining information for each feature and the designed part:*
 - (a) Identify the operation sequence of the designed part.
 - (b) Identify the operation type, the machine, and the cutting tool for each feature.
 - (c) Identify the tool approach/machining direction for each feature.
 - (d) Identify the removed machining volume for each feature.

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Computer-Aided Process planning (CAPP)

- Implementation consideration
 - Intelligent Feature Recognition Methodology (IFRM) Implementation

Table 10-6. Machining information (example 1)

| Operation | Feature | Feature | Operation |
|-----------|---------|--------------|------------------|
| sequence | ID | type | type |
| 1 | [3] | Slot_Through | Slotting_Milling |
| 2 | [2] | Step_blind | Shoulder_Milling |
| 3 | [4] | Pocket_Blind | Pocket_Milling |
| 4 | [5] | Hole_Through | Drilling |

Table 10-6. Machining information (example 1) (cont.)

| Operation sequence | Feature ID | Machine | Cutting tool | Tool Approach | Removed volume |
|--------------------|---------------|----------|------------------------|------------------------|----------------|
| 1 | [3] | Milling | End milling cutter | [0,1,0] or [0,-1,0] | 400.00 |
| 2 | [2] | Milling | Side milling cutter | [-1,0,0] or [0,1,0] | 180.00 |
| 3 | [4] | Milling | End milling cutter | [0,0,-1] | 120.00 |
| 4 | [5] | Drilling | Twist drill | [0,0,-1] | 804.25 |