

CAD/CAM (21-342)

*Advanced Manufacturing Laboratory
Department of Industrial Engineering
Sharif University of Technology*

Session # 8



Course Description

▪ *Instructor*

- *Omid Fatahi Valilai, Ph.D. Industrial Engineering Department, Sharif University of Technology*
- *Email: FValilai@sharif.edu, Tel: 6616-5706*
- *Website: Sharif.edu/~fvalilai*

▪ *Class time*

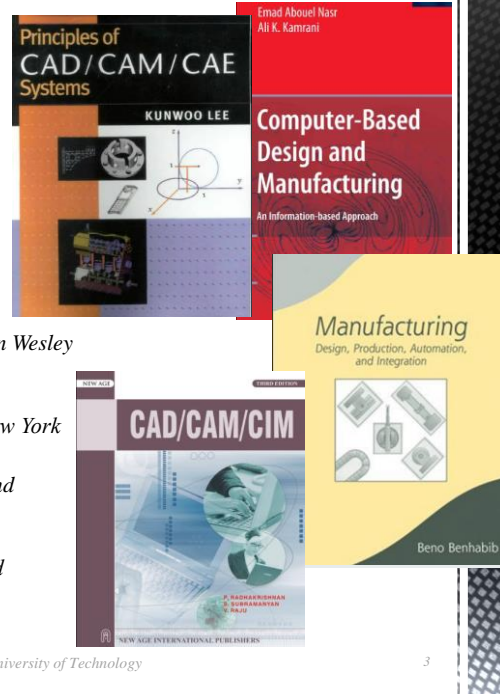
- *Saturday- Monday 10:30-12:00*

▪ *Course evaluation*

- *Mid-term (25%)*
- *Final exam (40%)*
- *Quiz (5%)*
- *Exercise (30%)*

Course Description (Continued ...)

- **Mid-term session:**
 - Monday: 8th Ordibehesht 1393, 10:30 ~ 12:30
- **Final Exam:**
 - Saturday: 24th Khordad 1393, 15:00 ~ 17:30
- **Reference:**
 - Lee, Kunwoo; "Principles of CAD/CAM/CAE systems", 1999, Addison Wesley
 - Abouel Nasr, Emad; Kamrani, Ali K.; "Computer-Based Design and Manufacturing: An Information-Based Approach", 2007, Springer, New York
 - Benhabib, Beno; "Manufacturing: Design, Production, CAD/CAM, and Integration", 2003, Marcel Dekker Inc, New York
 - Radhakrishnan, P.; Subramanian, S.; Raju, V.; "CAD/CAM/CIM", 3rd edition, 2005, New age international (P) limited publishers, New York



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Course Description (Continued..)

- **Contents:**
 - Introduction to CAD/CAM/CAE systems (5 sessions)
 - Components of CAD/CAM/CAE systems (2 sessions)
 - Geometric modeling systems (3 sessions)
 - Optimization in CAD (5 sessions)
 - Rapid prototyping and manufacturing (3 sessions)
 - Virtual engineering (2 sessions)
 - Product Life Cycle Cost Model (2 sessions)
 - Computer-Based Design and Features/Methodologies of Feature Representations (5 sessions)
 - Feature-Based Process Planning and Techniques (3 sessions)
 - Collaborative Engineering (2 sessions)

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Course Description (Continued..)

▪ Contents:

▪ Optimization in CAD

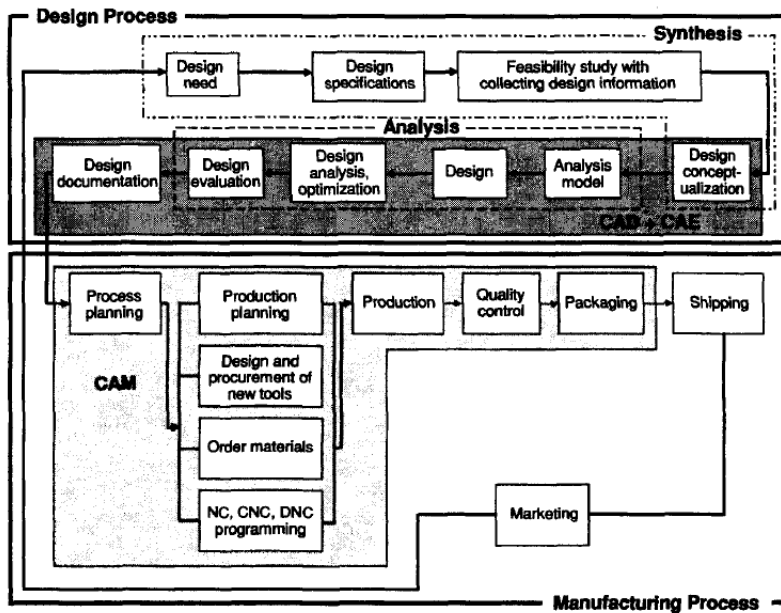
(5 sessions)

- Optimization of optimization problems
- Treatments of constraints
- Search models
- Simulated annealing
- Genetic algorithms
- Structural optimization

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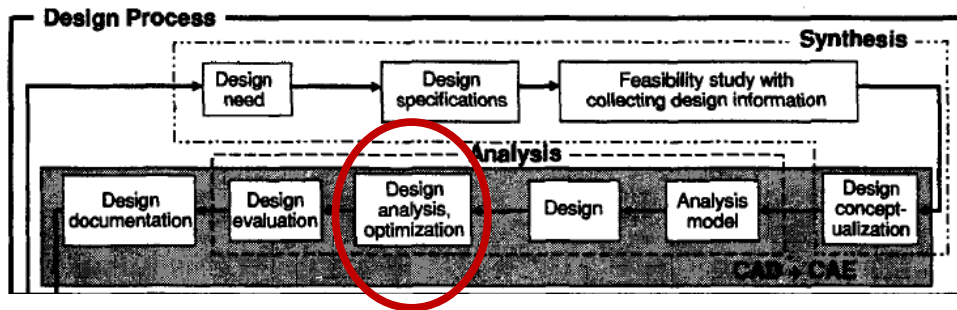
Introduction to CAD/CAM/CAE systems



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Geometric modeling systems

▪ Optimization in CAD



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Geometric modeling systems

▪ Optimization in CAD

▪ Design parameterization

- Designing a cylindrical pressure vessel: the parameter would be the mean diameter, the thickness, the height
- Depending on the situation some parameters can have constraints.
- The parameters which are going to be optimized are called Optimization Variables and the performance index is called Objective Function.

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Geometric modeling systems

- Optimization in CAD
 - Design parameterization

$$\mathbf{X}^* \in R^n \text{ so that } F(\mathbf{X}^*) = \min F(\mathbf{X})$$

subject to

$$\mathbf{X}_l \leq \mathbf{X}^* \leq \mathbf{X}_u$$

$$G_i(\mathbf{X}^*) \geq 0 \quad i = 1, 2, \dots, m$$

and

$$H_j(\mathbf{X}^*) = 0 \quad j = 1, 2, \dots, q$$

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Geometric modeling systems

- Optimization in CAD
 - Design parameterization
 - Terms:
 - Feasible design (acceptable design)
 - Regional constraints (Side constraints)
 - Behavior constraints (functional constraints)
 - The objective function $F(X)$ can be interpreted to be a surface face of dimension “n” embedded in a space of dimension “n+1”

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Geometric modeling systems

- *Optimization in CAD*
 - *Design parameterization*
 - *Treatment of constraints*
 - *For bounds we can restricts the design variables to stay within the specified bounds*
 - *For equality constraints the dimension of the design space is reduced by one for each constraint*
 - *Hence we may try to eliminate one design variable for each equality constraint.*
 - *For inequality constraints, we can modify the objective function to include the effect of the constraints*
 - *A penalty function may be added*

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Geometric modeling systems

- *Optimization in CAD*
 - *Design parameterization*
 - *Treatment of constraints*
 - *For inequality constraints, we can modify the objective function to include the effect of the constraints*
 - *A penalty function may be added*

$$P(\mathbf{X}) = \begin{cases} 0 & \text{for } \mathbf{X} \in R_f^n \\ +\infty & \text{for } \mathbf{X} \notin R_f^n \end{cases}$$

$$D(\mathbf{X}) = F(\mathbf{X}) + P(\mathbf{X})$$

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Geometric modeling systems

Optimization in CAD

- Design parameterization
- Treatment of constraints
 - Exterior penalty function

$$D(\mathbf{X}, \rho) = F(\mathbf{X}) + \frac{1}{\rho} S(\mathbf{X})$$

$$\min D(\mathbf{X}, \rho_k) = \min \left[F(\mathbf{X}) + \frac{1}{\rho_k} \left(\sum_i \delta_i |G_i(\mathbf{X})|^\alpha + \sum_j |H_j(\mathbf{X})|^\beta \right) \right]$$

$$S(\mathbf{X}) = \sum_i \delta_i |G_i(\mathbf{X})|^\alpha + \sum_j |H_j(\mathbf{X})|^\beta$$

$$\delta_j = \begin{cases} 0 & \text{if } G_j(\mathbf{X}) \geq 0 \\ 1 & \text{if } G_j(\mathbf{X}) < 0 \end{cases}$$

$$S(\mathbf{X}) = 0 \quad \text{if } \mathbf{X} \in R_f^n$$

$$S(\mathbf{X}) > 0 \quad \text{if } \mathbf{X} \notin R_f^n$$

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Geometric modeling systems

Optimization in CAD

- Design parameterization
- Treatment of constraints
 - Interior penalty function (no equality constraint may exist)

$$\min F(\mathbf{X})$$

$$G_i(\mathbf{X}) \geq 0 \quad i = 1, 2, \dots, m$$

$$B(\mathbf{X}) = \frac{1}{G_i(\mathbf{X})}$$

$$D(\mathbf{X}, \rho) = F(\mathbf{X}) + \rho B(\mathbf{X})$$

$$\min D(\mathbf{X}, \rho_k) = \min \left[F(\mathbf{X}) + \rho_k \sum_i \frac{1}{G_i(\mathbf{X})} \right]$$

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